

Piecewise

April 9, 2015

In [1]: %pylab inline

Populating the interactive namespace from numpy and matplotlib

In [2]: def p(t):

```
    if t < 1.00 : return 4E5 * t
    if t < 3.00 : return 2E5 * (3-t)
    return 0.00

mass = 6E05
T_n = 0.60
wn = 2*pi/T_n
k = mass*wn**2
zeta = 0.02
wd = wn * sqrt(1.00-zeta**2)
damp = 2*zeta*mass*wn
```

In [3]: h = 0.025

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cz = cos(wd*h)*exp(-zeta*wn*h)
sz = sin(wd*h)*exp(-zeta*wn*h)

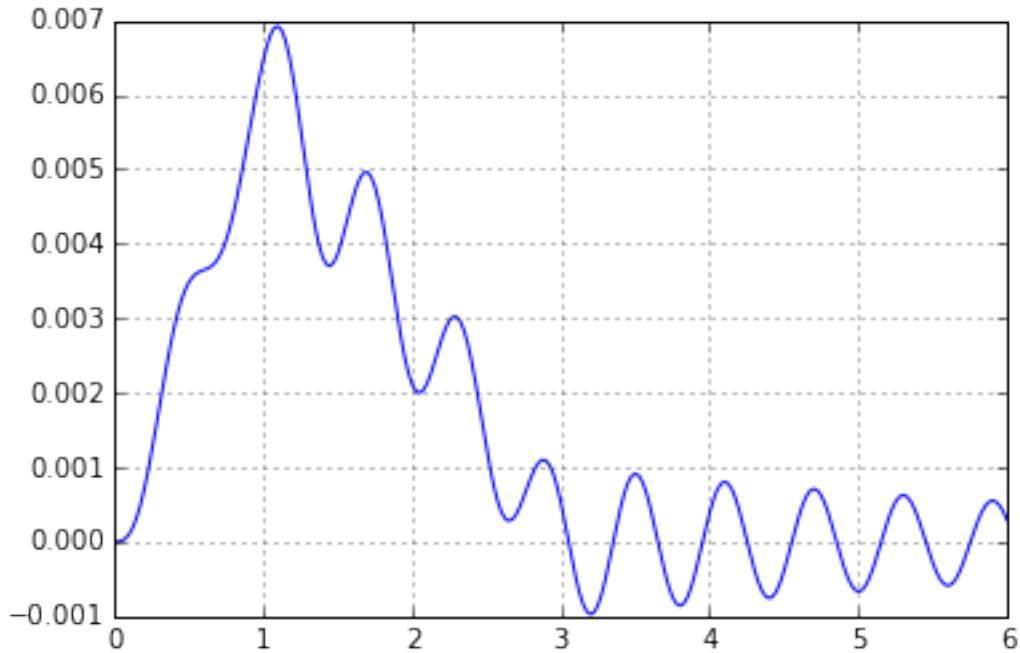
x_ = [] ; v_ = [] ; t_ = []

t = 0.00 ; X = 0.00 ; V = 0.00 ; P = p(t)
```

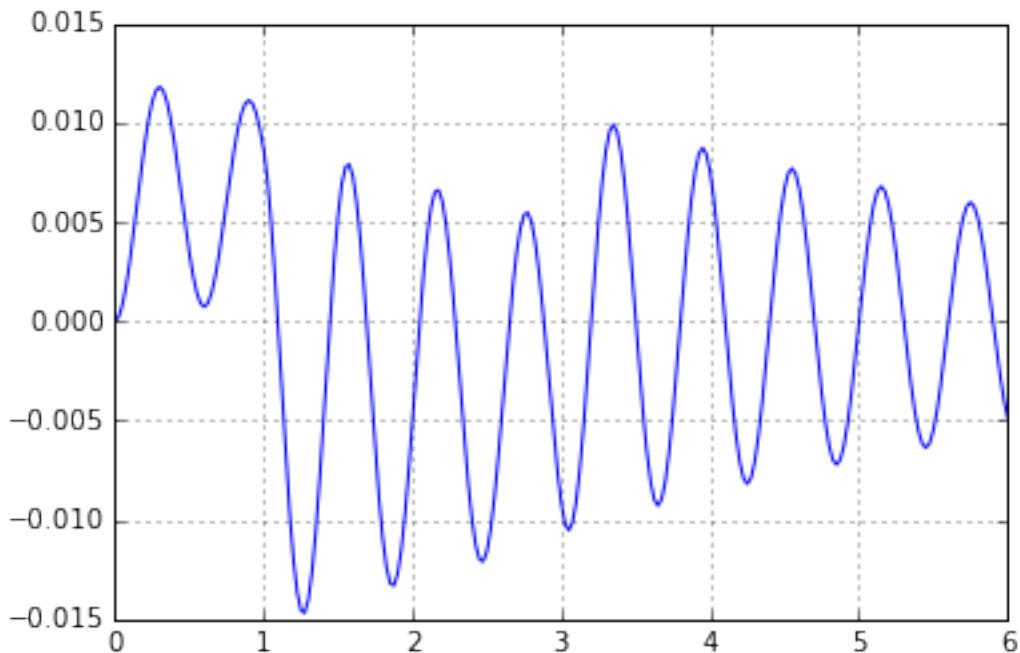
In [4]: while t < 6.001:

```
x_.append(X) ; v_.append(V) ; t_.append(t)
# print "%6.3f %+12.10f %+12.10f" % (t, X, V)
t = t+h
Ph = p(t)
dx = P/k
ddx = (Ph-P)/k
B = X + 2*zeta*ddx/wn/h - dx
A = (V + zeta*wn*B - ddx/h)/wd
X = A*sz + B*cz + dx + ddx*(1-2*zeta/wn/h)
V = (A*(wd*cz-zeta*wn*sz) -
      B*(wd*sz+zeta*wn*cz) + ddx/h)
P = Ph
```

In [7]: plot(t_, x_); xlim((0,6)); grid();



```
In [8]: plot(t_, v_); xlim((0,6)); grid()
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In [6]:
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