Homework no. 2

To have your homework corrected, please hand it on Thursday, April 4^{ts}.



A single,uniform, simply supported beam supports two masses $m_1 = m$ and $m_2 = 3m$. Neglecting the axial deformability and the beam's mass, the system has two dynamic degrees of freedom, x_1 and x_2 as indicated in sub-figure (a). For the degrees of freedom x_1 , x_2 and x_3 (again, see sub-fig. (a)) the flexibility matrix is

$$\mathbf{F} = \frac{1}{6} \frac{EJ}{L^3} \begin{vmatrix} 48 & 27 & 58 \\ 27 & 16 & 32 \\ 58 & 32 & 72 \end{vmatrix}$$

1. For the dynamic 2 DoF system determine: (a) the mass matrix **M**, (b) the stiffness matrix **K**, (c) the eigenvalues, normalized with respect to $\omega_0^2 = EJ/mL^3$, (d) the eigenvectors, normalized using $\psi_{1i} = 1$ for $\forall i$, (e) the modal mass matrix **M**^{*} and (f) the modal stiffness matrix **K**^{*}.

With reference to sub-figure (b), the system is at rest when it is affected by a

dynamic load acting on the non-dynamic DoF x_3 ; with $\omega_0 t_0 = 4\pi$ it is

$$p(t) = \begin{cases} 0\\ 0\\ P_0 \end{cases} f(t), \quad \text{with } f(t) = \begin{cases} 4\frac{t}{t_0} \left(1 - \frac{t}{t_0}\right) & 0 \le t \le t_0, \\ 0 & \text{otherwise.} \end{cases}$$

- 2. Find the equivalent load vector, acting on the dynamic degrees of freedom, using the static condensation procedure.
- 3. Write the two equations of motion in modal coordinates.
- 4. Determine the particular integrals and write the expressions of modal responses for $0 \le t \le t_0$.
- 5. Plot the modal responses in the same interval.
- 6. Write the expressions of the masses' displacements in the same interval.
- 7. Plot the masses' displacements.
- 8. Compare with the results of numerical integration use the constant *and* the linear acceleration algorithm with the same time step $h = T_1/12$, where $T_1 = 2\pi/\omega_1$ is the natural period of vibration.

With reference to sub-figure (c), the system is at rest when it is affected by an imposed horizontal displacement of the hinge at the bottom right,

$$u(t) = \delta \begin{cases} 0 & t \le t_0, \\ \frac{t}{t_0} - \frac{\sin(2\pi t/t_0)}{2\pi} & 0 \le t \le t_0, \\ 1 & t_0 \le t, \end{cases}$$

where δ is the final value of the imposed displacement (note that the horizontal displacement of the roller is equal to zero).

- 9. Plot u(t) and $\ddot{u}(t)$ in the interval $0 \le t \le t_0$.
- 10. Sketch the rigid motion of the beam that is possible when you downgrade the hinge to a roller to permit its horizontal displacement.
- 11. Determine the influence matrix **E**.
- 12. Write the equations of motion in modal coordinates.
- 13. Write the expressions of the particular integrals and of the modal responses.
- 14. Plot the *total* displacement of the left mass.